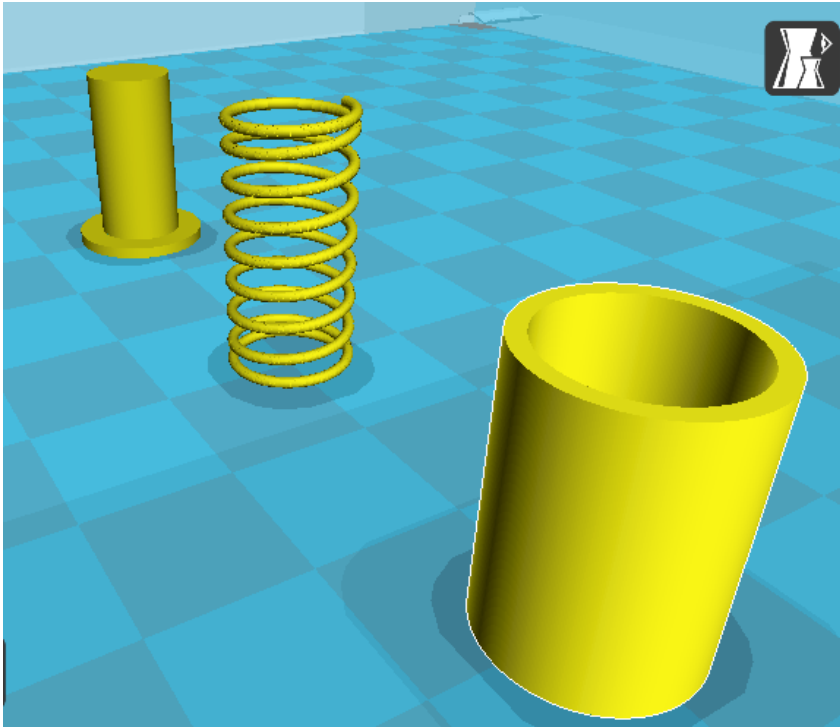
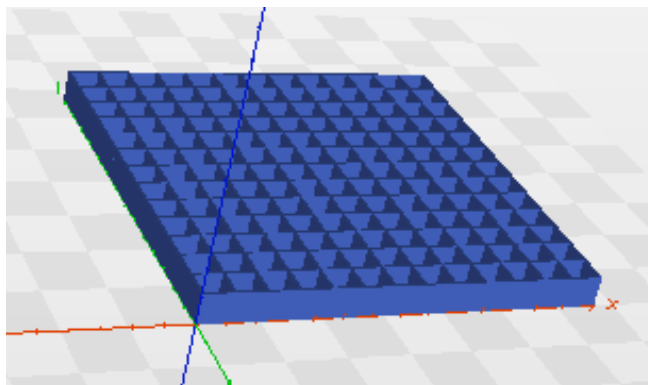


by Fritz Ruoss

FED1+: Produce Tools and Utilities for Compression Springs on 3D Printer

Mandrel and bore (bush) for the calculated compression spring can be created by FED1+ as STL file and printed on 3D printer. Moreover, a “typecase” to be used for presetting of the compression springs to reduce relaxation. Question to FED users: any suggestions to create other useful 3D printable tools and utilities for production, assembly, measuring and testing of compression springs? [Mailto:Fritz.Ruoss@hexagon.de](mailto:Fritz.Ruoss@hexagon.de)

**FED12: Elastomer spring as STL Model**

FED12 creates 3D model of cylindrical rubber spring.

Software Bundle – Complete Spring Package

HEXAGON Complete Spring Package for 4985 Euro (standalone license) includes a total of 17 spring calculation programs (FED1+,2+,3+,4,5,6,7,8,9,10,11,12,13,14,15,16,FED17).

GR1: Planetary Differential

A planetary differential gear is made of 2 planetary stages without ring wheels. With common carrier, where the planetary wheels drive each other ($n_{P2} = -n_{P1} \cdot z_{P1} / z_{P2}$).

Design is comparable with a Ravigneux gear without ring wheel, and can be calculated like a Ravigneux Gear. For transmission ratio 1, set $i_{0i} = -i_0$ and ring gear = idle.

Gear Stage 1 X

Gear Type

- Spur/Helical Gear
- Planetary Gear
- Ravigneaux
- Simpson
- Plus Planetary Gear
- HCX Planetary Pair
- Stepped Planet
- Differential Spur Gear

n in <

$iS = z_{Se}/z_{Si}$ <

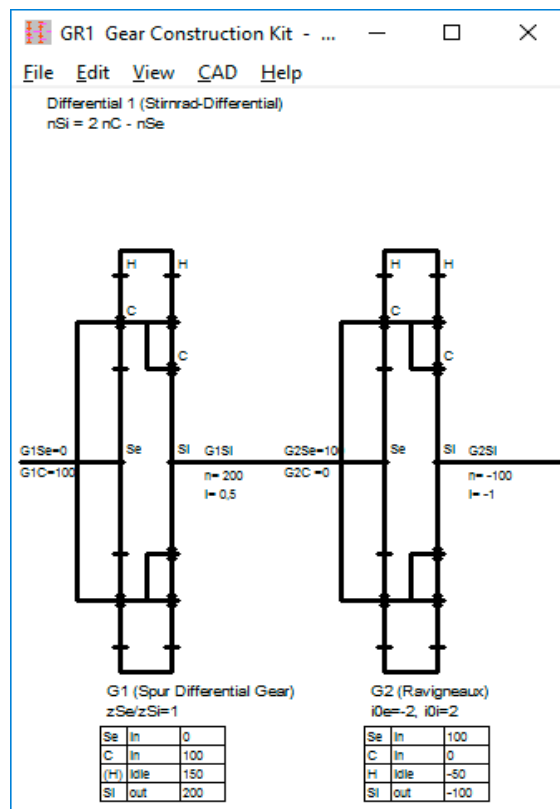
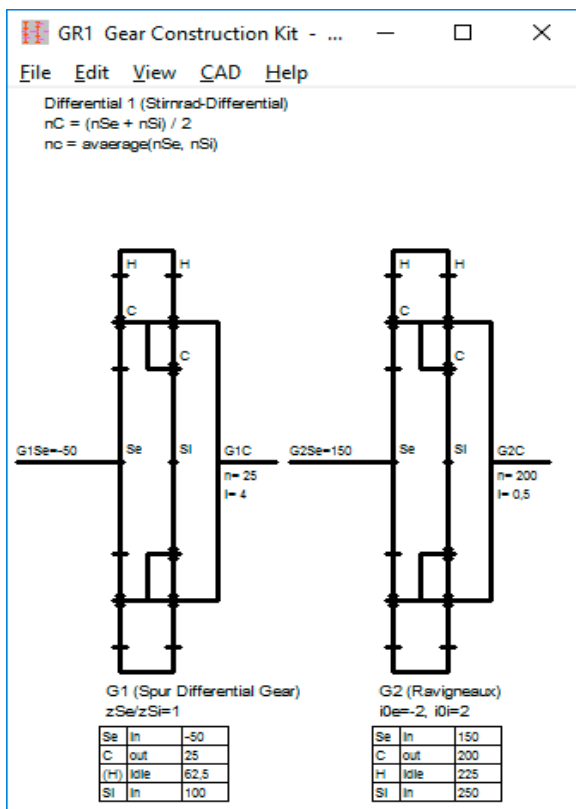
Name

Driven by...

Drive Type	Gear No.	Element	n [1/min]
Sun Se	in	..	-50
Planet Carrier C	out		
Sun Si	in	..	100

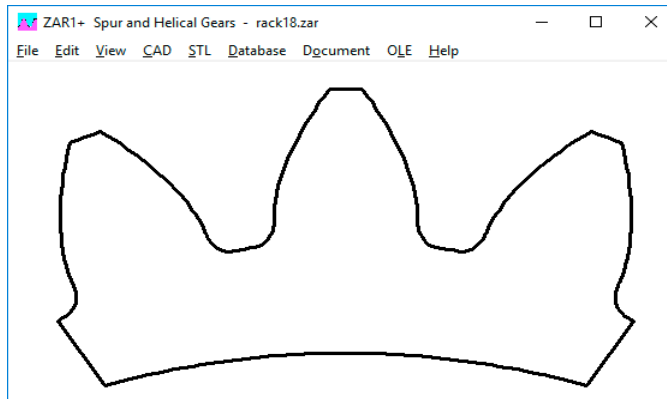
Primarily, we define both sun wheels Se and Si as input shafts. Output shaft is the planet carrier (C): $n_C = (n_{Si} + n_{Se}) / 2$. Output speed is mean value of input speeds.

Next, we define Se and C as input shaft, and get $n_{Si} = 2 \cdot n_C - n_{Se}$. If input shaft Se is blocked ($n_{Se} = 0$), n_{Si} runs with double input speed ($2 \cdot n_C$). And if planet carrier is blocked ($n_C = 0$), n_{Si} runs with inverse input speed ($n_{Si} = -n_{Se}$).

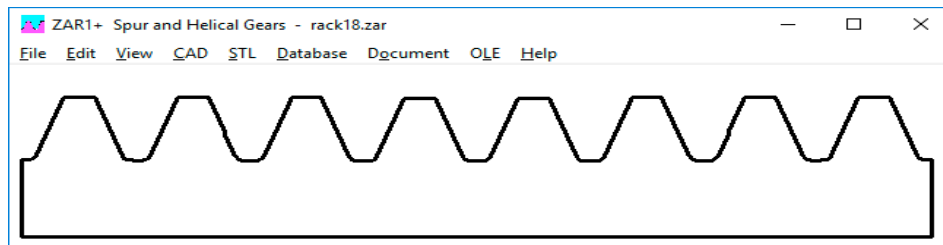


ZAR1+: Sector Gear for CAD, STL

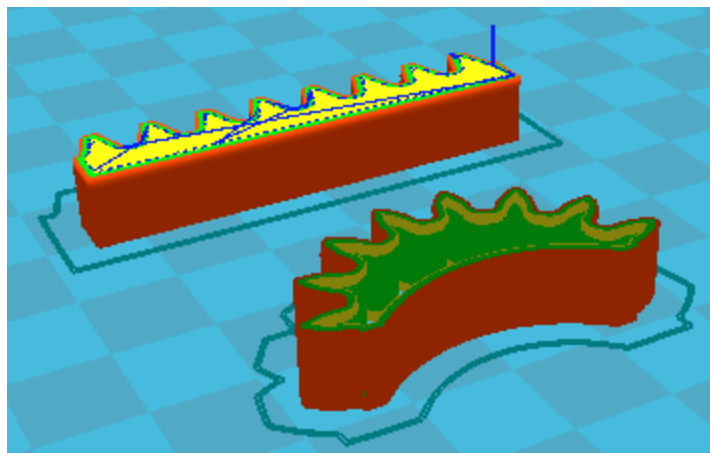
Instead of a gear wheel, you now also can generate a sector of a gear wheel as CAD file or STL file. Enter number of teeth, and ZAR1+ generates a sector gear over n teeth.



This option also can be used to generate a rack.

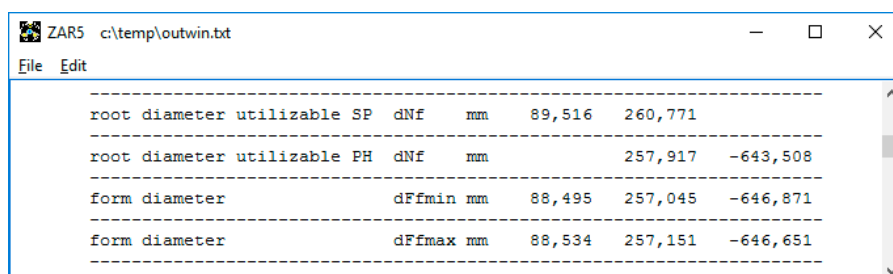


Sectors and racks with spur toothing ($\beta=0^\circ$) can be printed with 3D printer.



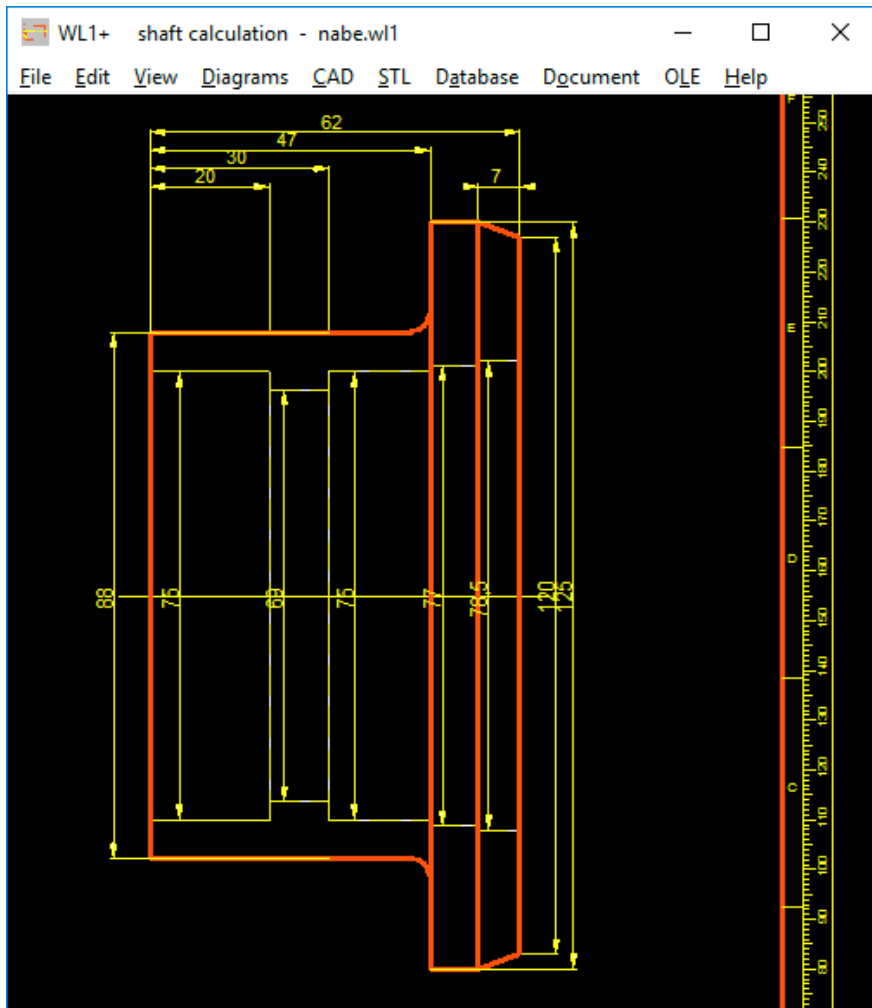
ZAR5: Form diameter dFf

Form diameters for sun wheel, planet wheel and ring wheel were added to ZAR5 printout.



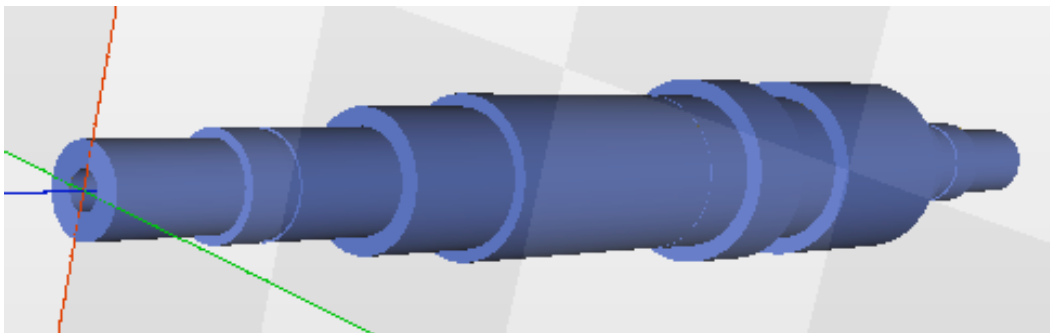
WL1+: Bore diameters dimensioned

Dimensions of bore diameters have been added to production drawing of hollow shafts.



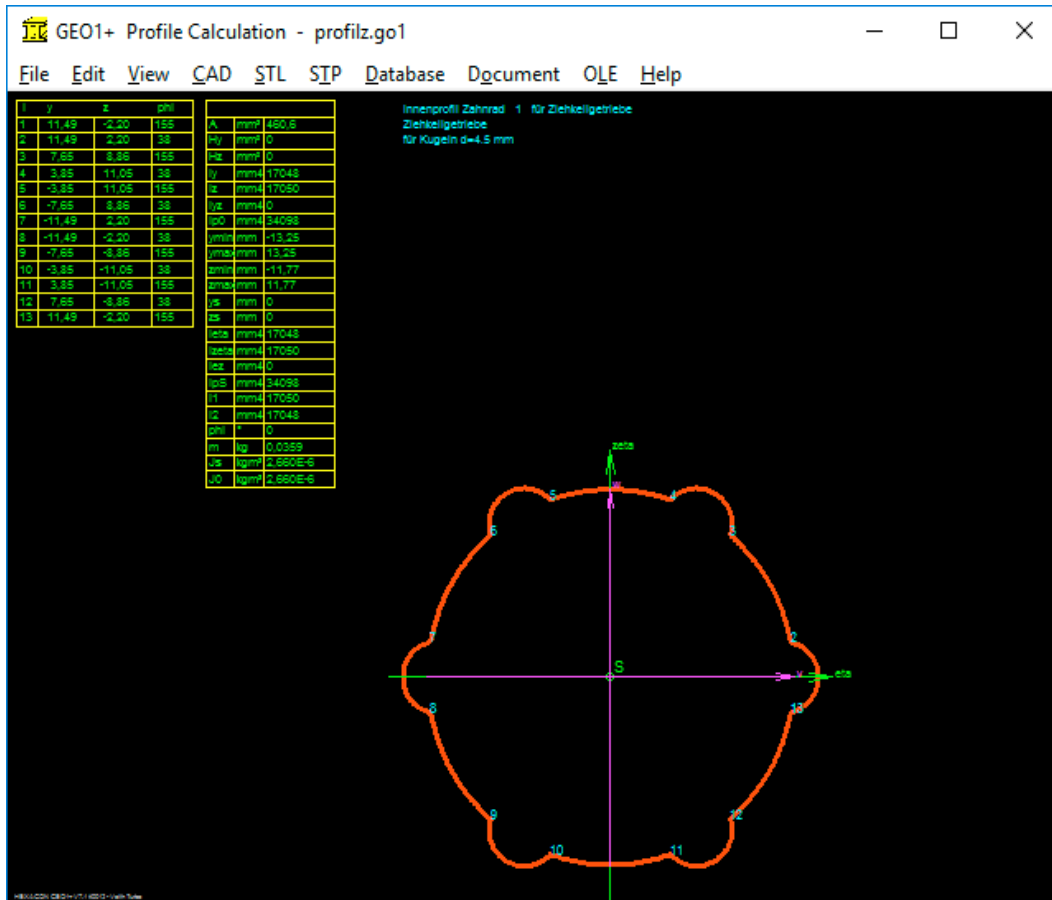
WL1+: STL closed solid

Until now, STL volume was created by lateral surfaces of the cylinders. No problem for 3D printing, but in STL viewer shaft appears hollow. Thus frontal surfaces were closed now.

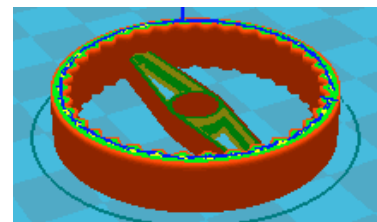
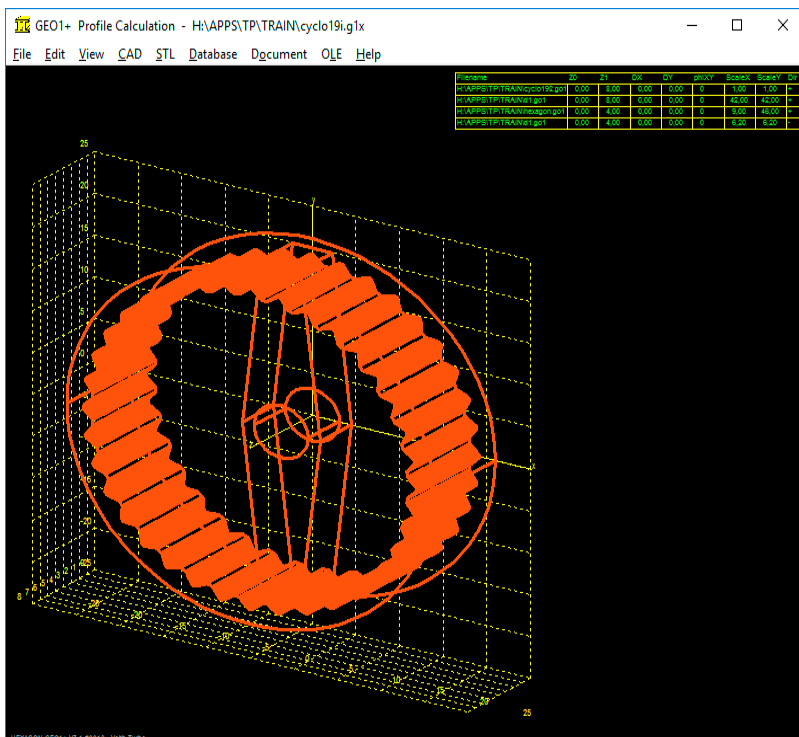


GEO1+: Quick3 View

New Quick3 View of the profile calculation software now shows profile drawing and tables with coordinates and calculation results on one screen.

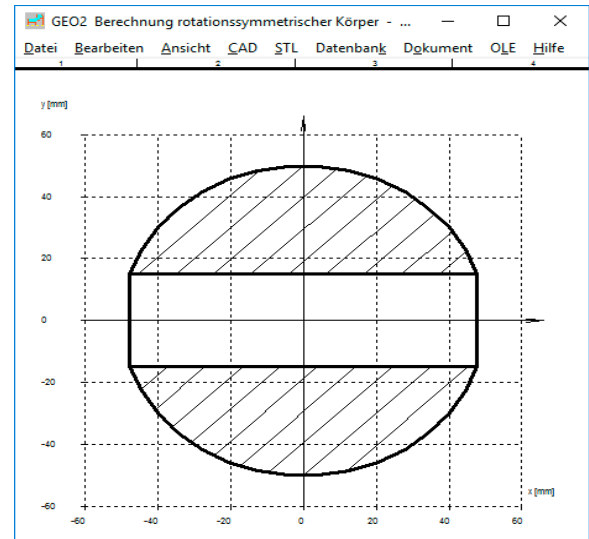
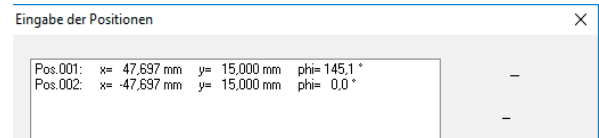
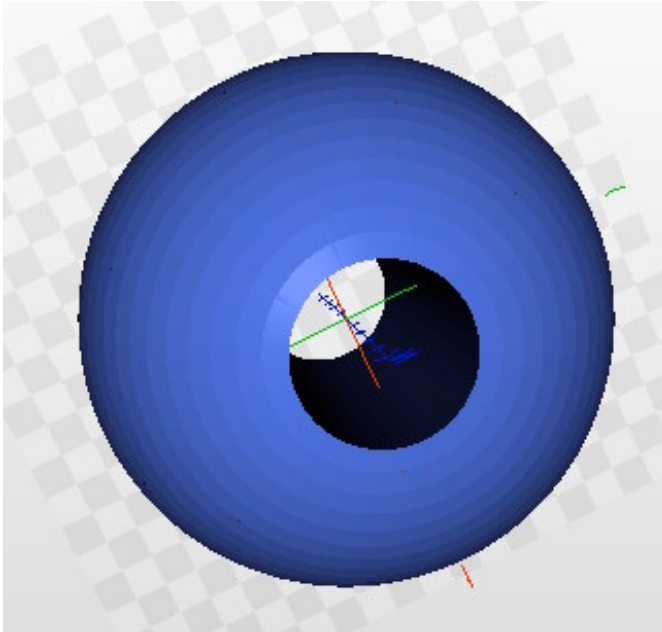


If you used the multi layer option to connect different profiles to one volume, new Quick 3 View shows a 3D drawing and tables with GEO1 elements (file name, scale, shift, rotation, direction).



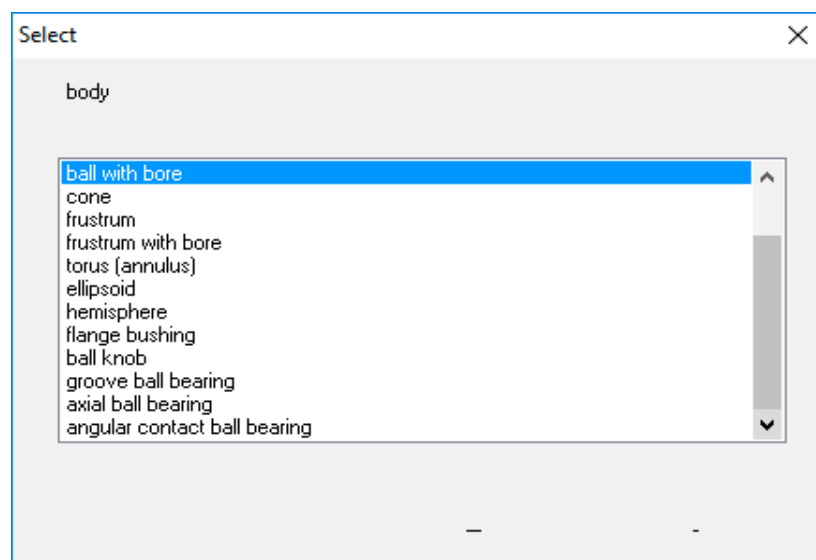
GEO2: STL Solid Model

GEO2 calculates volume, masse and mass moment of inertia of any rotationally symmetric body. Geometrical body is defined by input of xy coordinates of the section area (half-section). For example, you can define a sphere with bore by input of only 2 drawing elements: a straight line and an arc in a xy plane. New version 3.0 of GEO2 can generate a STL file of the solid model.



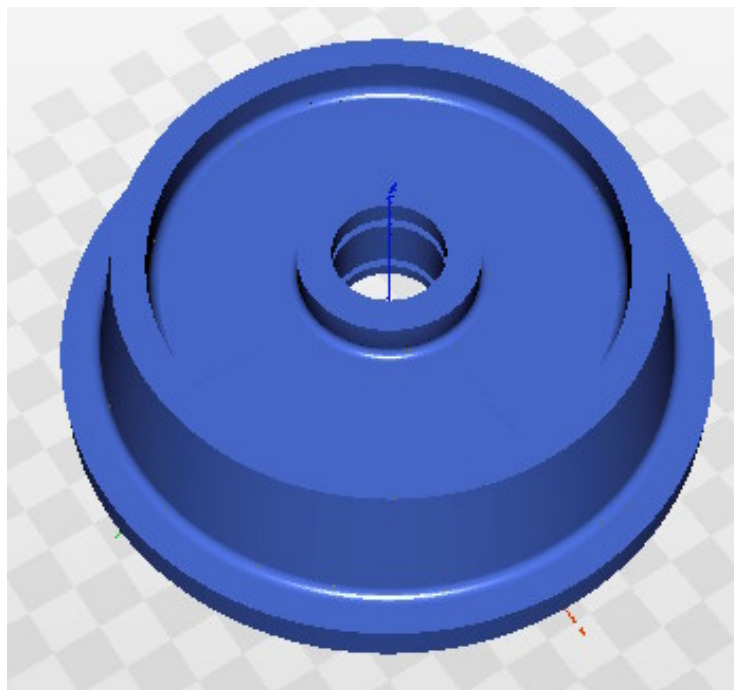
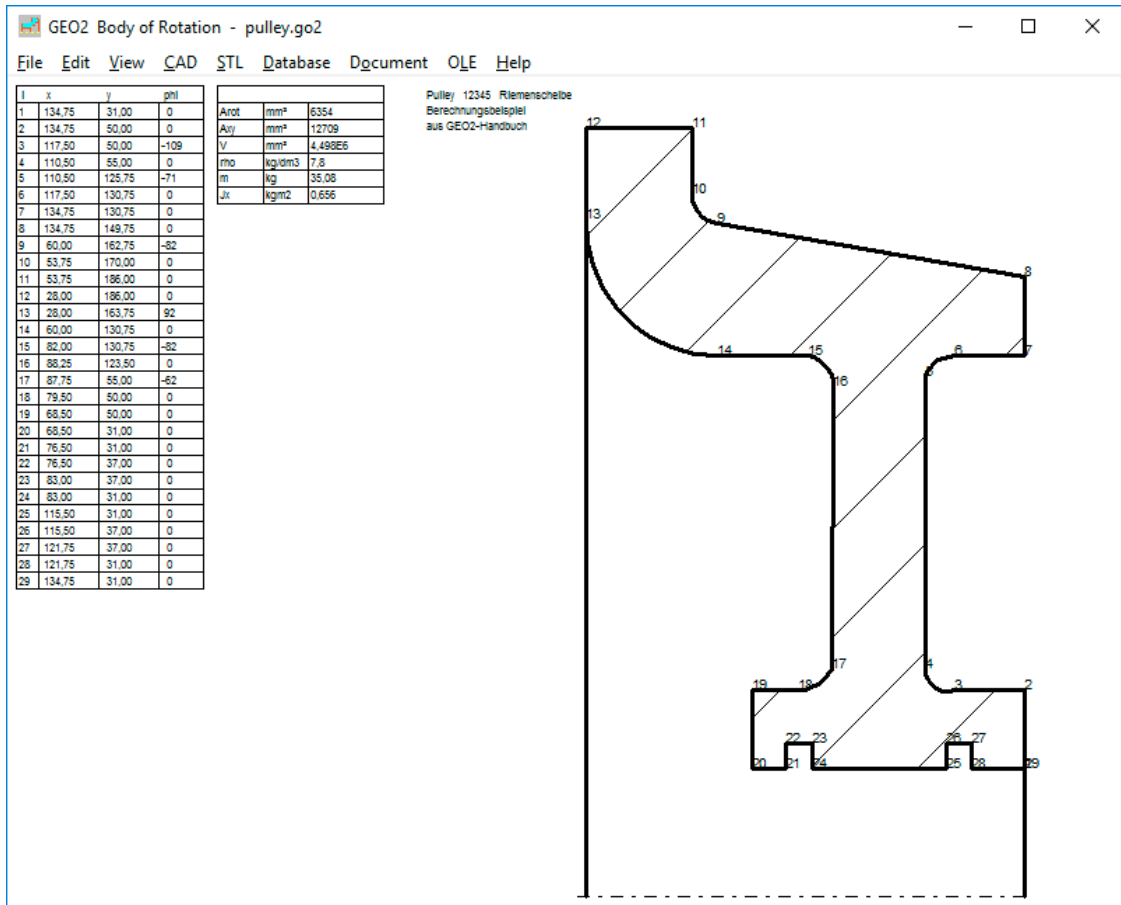
GEO2 Generate Predefined Standard 3D Models:

GEO2 generates coordinates of standard models like cylinder, sphere, cone, frustrum, torus, ellipsoid, hemisphere flange bushing, ball knob by input of few parameters. And outer ring and inner ring of groove ball bearing, axial ball bearing, angular contact ball bearing.



GEO2: Quick3 View

Quick1 View and Quick3 View show tables with coordinates and calculation results and a sectional drawing altogether on one screen.

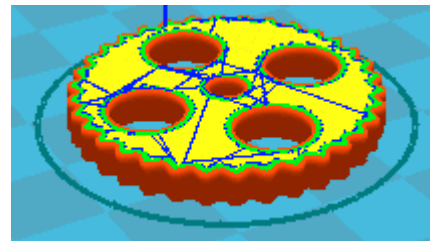
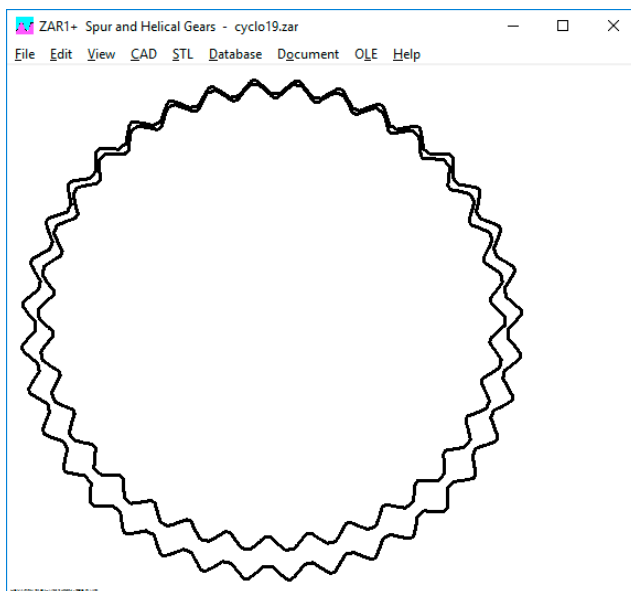


Tip: Design Cycloid Gear with involute gear wheels by means of ZAR1+

By rolling off a gear wheel in a ring wheel you can realize a gear with large transmission ratio with relative small dimensions, if difference in number of teeth between external and internal wheel is low. Gear wheel is driven by an eccentric shaft, output is rotation of the same gear wheel relative to center of the fixed ring wheel. Similar gears according to this principle are known as „Cyclo Gear“ (Sumitomo, Markt Indersdorf), but with special cycloide toothing instead of ordinary involute toothing.

Transmission ratio is $i = z1 / (|z2| - z1)$. Highest transmission ratio can be achieved if number of teeth of the cog wheel is 1 less than number of teeth of the ring wheel. To avoid teeth collision, tooth height must be reduced and pressure angle increased.

Example: $z1=34$, $z2=-36$, $m=1$, $\alpha=45^\circ$, tooth height coefficients $0.6*m$ and $0.45*m$. Center distance 1mm is eccentricity of the driving shaft, transmission ratio = 1:17.



Nuisance: German Telecom wants money for a dead phone line

Our offices in Neidlingen and Berlin are without fixed phone line since years, because German Telecom failed or was not willing to repair the broken phone line. Therefore we terminated the contract without notice, and switched phone and internet to mobile. Now HEXAGON GmbH was sued by Telekom Deutschland GmbH for payment of the retained fees (of 211 euros) for the faulty connections. In return, she receives a counterclaim from us for damages for non-availability due to the disturbed telephone connections. If you could not reach us in 2014 or 2016 in Berlin (+49-30-28096996) or Neidlingen (+49-7023-909567) because of disruption of the line, we ask for notification. Allegedly the disturbance must be proved by the Telecom customer, a confirmed disturbance report is not sufficient as proof. Already won: the remaining two telephone lines in Kirchheim were consequently terminated promptly after filing a claim with Deutsche Telekom and switched via FritzBox Cable to TV cable of Unitymedia: faster Internet for less money. German Telecom? Never again!

30 years HEXAGON Software with prices like 30 years ago

Since 1988, is HEXAGON software is on the market. The first programs were TOL1, ZAR1 and FED1. The programs ran under MS-DOS and were delivered on 5.25" floppy disks 360 kB. In order to offer prices like 30 years ago, no price list has to be rewritten: most prices remained almost the same over the years. For example, FED1 + cost 1350 Deutsche Mark at that time, today 695 Euro.

HEXAGON PRICELIST 2018-03-01

PRODUCT	EUR
DI1 Version 1.2 O-Ring Seal Software	190,-
DXF-Manager Version 9.1	383,-
DXFPLOT V 3.2	123,-
FED1+ V30.0 Helical Compression Springs incl. spring database, animation, relax., 3D,..	695,-
FED2+ V20.6 Helical Extension Springs incl. spring database, animation, relaxation, ...	675,-
FED3+ V19.1 Helical Torsion Springs incl. prod.drawing, animation, 3D, rectang.wire, ...	480,-
FED4 Version 7.3 Disk Springs	430,-
FED5 Version 15.7 Conical Compression Springs	741,-
FED6 Version 16.3 Nonlinear Cylindrical Compression Springs	634,-
FED7 Version 13.3 Nonlinear Compression Springs	660,-
FED8 Version 7.0 Torsion Bar	317,-
FED9 Version 6.0 Spiral Spring	394,-
FED10 Version 4.1 Leaf Spring	500,-
FED11 Version 3.3 Spring Lock and Bushing	210,-
FED12 Version 2.5 Elastomer Compression Spring	220,-
FED13 Version 4.0 Wave Spring Washers	228,-
FED14 Version 2.0 Helical Wave Spring	395,-
FED15 Version 1.4 Leaf Spring (simple)	180,-
FED16 Version 1.1 Constant Force Spring	225,-
FED17 Version 1.3 Magazine Spring	725,-
GEO1+ V7.1 Cross Section Calculation incl. profile database	294,-
GEO2 V3.0 Rotation Bodies	194,-
GEO3 V3.3 Hertzian Pressure	205,-
GEO4 V4.2 Cam Software	265,-
GEO5 V1.0 Geneva Drive Mechanism Software	218,-
GEO6 V1.0 Pinch Roll Overrunning Clutch Software	232,-
GR1 V2.1 Gear construction kit software	185,-
HPGL-Manager Version 9.1	383,-
LG1 V6.6 Roll-Contact Bearings	296,-
LG2 V2.2 Hydrodynamic Plain Journal Bearings	460,-
SR1 V22.8 Bolted Joint Design	640,-
SR1+ V22.8 Bolted Joint Design incl. Flange calculation	750,-
TOL1 V12.0 Tolerance Analysis	506,-
TOL2 Version 4.0 Tolerance Analysis	495,-
TOLPASS V4.1 Library for ISO tolerances	107,-
TR1 V5.0 Girder Calculation	757,-
WL1+ V21.1 Shaft Calculation incl. Roll-contact Bearings	945,-
WN1 Version 12.0 Cylindrical and Conical Press Fits	485,-
WN2 V10.1 Involute Splines to DIN 5480	250,-
WN2+ V10.1 Involute Splines to DIN 5480 and non-standard involute splines	380,-
WN3 V 5.4 Parallel Key Joints to DIN 6885, ANSI B17.1, DIN 6892	245,-
WN4 V 4.7 Involute Splines to ANSI B 92.1	276,-
WN5 V 4.7 Involute Splines to ISO 4156 and ANSI B 92.2 M	255,-
WN6 V 3.0 Polygon Profiles P3G to DIN 32711	180,-
WN7 V 3.0 Polygon Profiles P4C to DIN 32712	175,-
WN8 V 2.2 Serration to DIN 5481	195,-
WN9 V 2.2 Spline Shafts to DIN ISO 14	170,-
WN10 V 4.2 Involute Splines to DIN 5482	260,-
WN11 V 1.3 Woodruff Key Joints	240,-
WNXE V 2.1 Involute Splines - dimensions, graphic, measure	375,-
WNXK V 2.0 Serration Splines - dimensions, graphic, measure	230,-
WST1 V 10.2 Material Database	235,-
ZAR1+ V 26.2 Spur and Helical Gears	1115,-
ZAR2 V8.0 Spiral Bevel Gears to Klingelnberg	792,-
ZAR3+ V9.0 Cylindrical Worm Gears	620,-
ZAR4 V5.2 Non-circular Spur Gears	1610,-
ZAR5 V11.6 Planetary Gears	1355,-
ZAR6 V4.0 Straight/Helical/Spiral Bevel Gears	585,-
ZAR7 V1.4 Plus Planetary Gears	1380,-

ZAR8 V1.4 Ravigneaux Planetary Gears	1950,-
ZARXP V2.2 Involute Profiles - dimensions, graphic, measure	275,-
ZAR1W V2.0 Gear Wheel Dimensions, tolerances, measure	450,-
ZM1.V2.5 Chain Gear Design	326,-

PACKAGES	EUR
HEXAGON Mechanical Engineering Package (TOL1, ZAR1+, ZAR2, ZAR3+, ZAR5, ZAR6, WL1+, WN1, WN2+, WN3, WST1, SR1+, FED1+, FED2+, FED3+, FED4, ZARXP, TOLPASS, LG1, DXFPLOT, GEO1+, TOL2, GEO2, GEO3, ZM1, WN6, WN7, LG2, FED12, FED13, WN8, WN9, WN11, DI1, FED15, WNXE, GR1)	8,500.-
HEXAGON Mechanical Engineering Base Package (ZAR1+, ZAR3+, ZAR5, ZAR6, WL1+, WN1, WST1, SR1+, FED1+, FED2+, FED3+)	4.900,-
HEXAGON Spur Gear Package (ZAR1+ and ZAR5)	1,585.-
HEXAGON Planetary Gear Package (ZAR1+, ZAR5, ZAR7, ZAR8, GR1)	3,600.-
HEXAGON Involute Spline Package (WN2+, WN4, WN5, WN10, WNXE)	1,200.-
HEXAGON Graphic Package (DXF-Manager, HPGL-Manager, DXFPLOT)	741.-
HEXAGON Helical Spring Package (FED1+, FED2+, FED3+, FED5, FED6, FED7)	2,550.-
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- **Swedish**: FED1+, FED2+, FED3+, FED5, FED6, FED7.
- **Portugues**: FED1+, FED17
- **Spanish**: FED1+, FED2+, FED3+, FED17

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Software Update (software 64-bit Win + pdf manual)	50,-

Update Mechanical Engineering Package: 800 EUR, Update Complete Package: 1000 EUR

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Conditions of payment: bank transfer in advance with 2% discount, or by credit card (Master, Visa) net.

Key Code

After installation, software has to be released by key code. Key codes will be sent after receipt of payment.

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