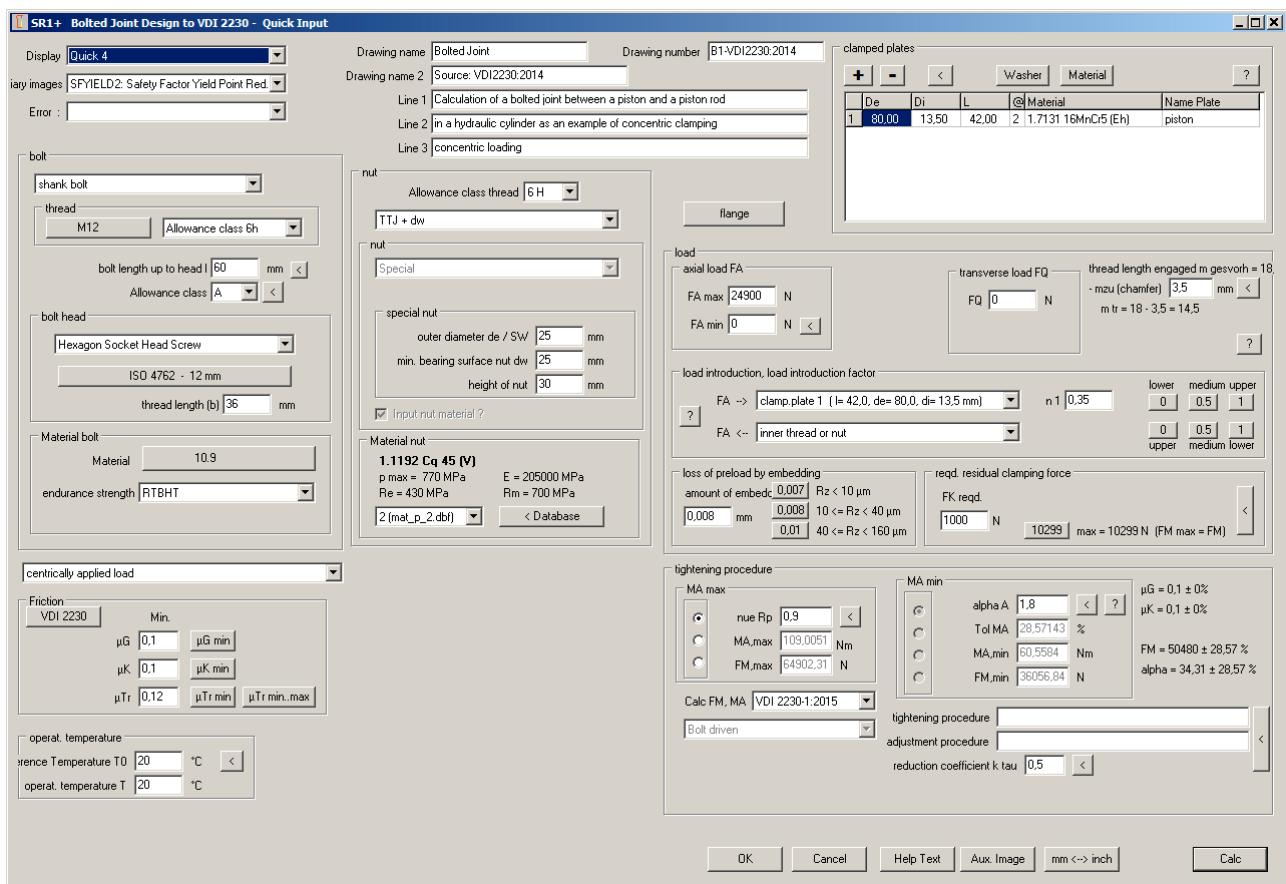


by Fritz Ruoss

SR1+: Quick Input Window

New Quick Input Window of SR1 and SR1+ integrates all former input windows in only one dialogue window.



Quick Input Window provides a new option if you want to study the influence of one or more parameters in a specific diagram: select required diagram at „Display“, then change input value and click „Calc“ button to actualize the diagram. Until now, you could do so with the result graphic (Quick3) only.

If you configure help level 2, Quick Input opens automatic at program start.

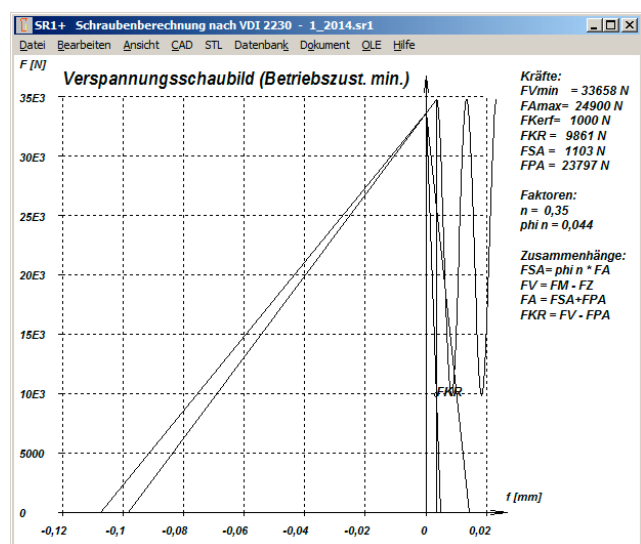
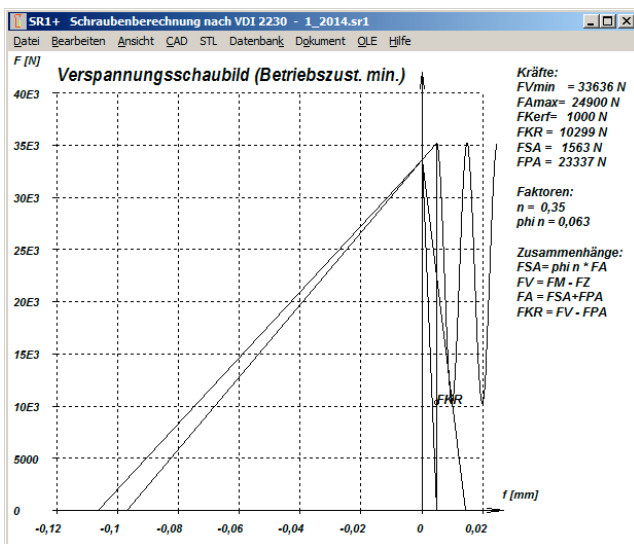
The new Quick Input window in SR1+, due to large variety of input values, became relative large, 1280x900 pixel. If you want to display it together with the graphic result window on one screen, resolution should be 2560x1080 or higher. Minimum screen resolution required for SR1+ Quick Input is 1280x1024, but in this case result graphic window is covered completely by the Quick Input window.

You can skip Quick Input, well-known input windows of earlier versions are available furthermore.

SR1+: Compare FKR in Load-Extension Diagram

A customer asked why the residual clamping load FKR is not equal with the point of intersection in the load-extension diagram, as shown in VDI2230-1 figure 2. In fact, FKR is the intersection point for TBJ with bolt, but not for TTJ. And the reason is the “supplement for plate resilience δP_{zu} ” (equation 80,81,82). Thus, for TTJ the axial additional load FSA no longer calculated from the ratio of δP and δS only, but distorted by δP_{zu} . Deviation is huge, using example 1 of VDI 2230, FKR is calculated 10.3kN, but the intersection point in the diagram is only 2 kN. Deformation f_{PA} is calculated with δP , not $(\delta P + \delta P_{zu})$.

To get residual clamp load for TTJ from the intersection point of the diagram, you either must switch to TBJ, or at “Edit->Calculation method” “Elasticity” switch to „deformation sleeve (VDI2230-1986)“. Then select “Load-Extension diagram->working condition min.” to display residual clamp load FKR.



B1 of VDI 2230-1: FKR does not intersect in FKR

B1 as TBJ: FKR correct in intersection point

To get the required residual clamp load “FKerf” instead of “FKR”, display “Load-Extension diagram->working condition reqrd.”. Same situation here: intersection point is correct for TBJ, but not for TTJ.

It seems that equation (80) in VDI2230-1:2015 is wrong.

$\Phi_K = \delta P / (\delta S + \delta P)$ is the deformation ratio of plate load ratio. If " δP_{zu} " used in numerator to increase δP , it must also be used in denominator to increase δP .

According to VDI 2230-1:2015: $\delta P_{zu} = (w-1) * \delta M$

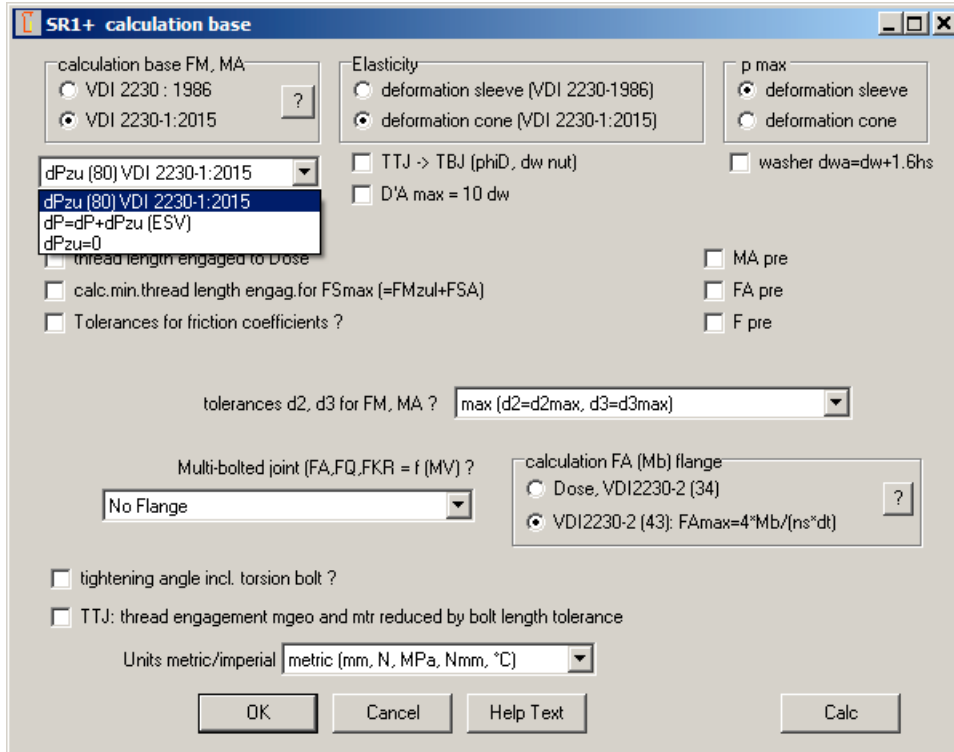
According to VDI, w is the „joint coefficient for the type of bolted joint“. w is predefined for two values only: w=2 for TTJ and w=1 for TBJ

To say it less complicated and more straightforward than VDI, without w:

$\delta P_{zu} = \delta M$ for TTJ

$\delta P_{zu} = 0$ for TBJ

SR1+: Calculation Method δP_{zu}

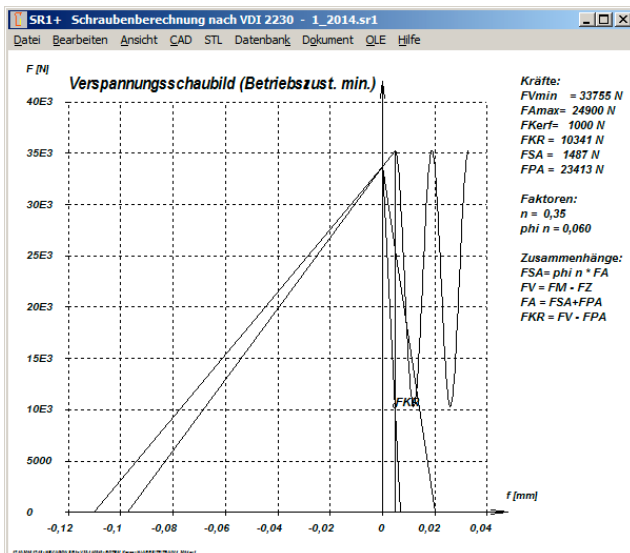


In SR1 and SR1+, you can now configure at “calculation method”:

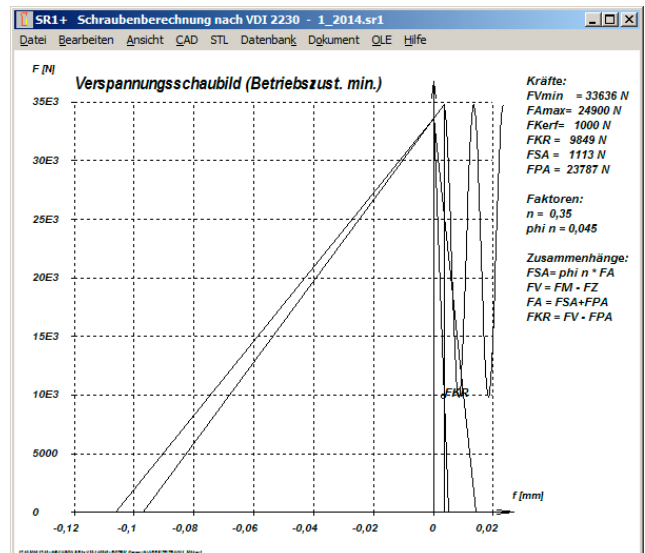
1. δP_{zu} (80) VDI2230-1:2015: ϕK calculated according to VDI2230-1:2015
2. $\delta P = \delta P + \delta P_{zu}$ (TTJ): if TTJ, elasticity of nut thread " δP_{zu} " added to δP .
3. $\delta P_{zu} = 0$: elasticity of nut thread not considered (as for TBJ).

Use default method 1 if you think that calculation according to VDI2230-1:2015 is correct.

Configure method 2 if elasticity of nut thread should be considered in δP . Configure method 3 if elasticity of nut thread should not be considered in δP .



Example 1 of VDI 2230-1 with $\delta P = \delta P + \delta P_{zu}$

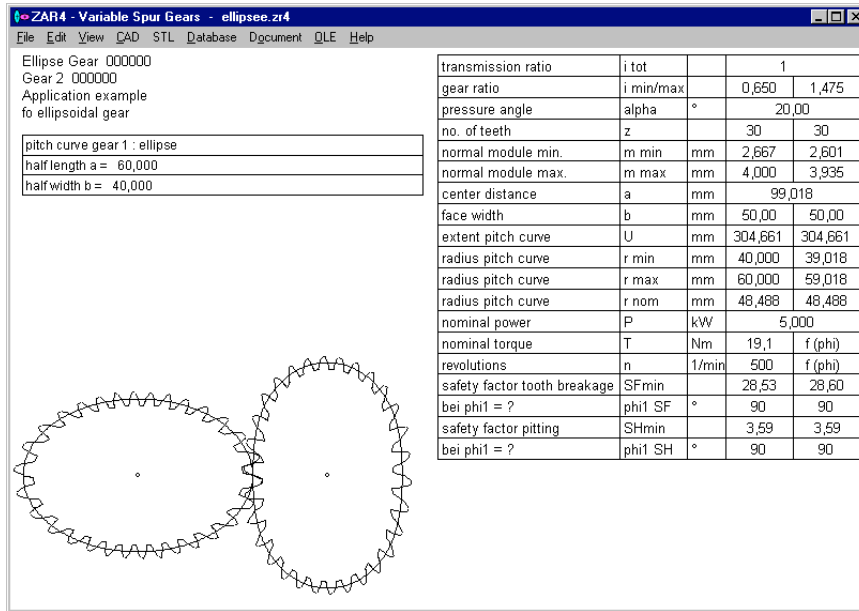


Example 1 of VDI2230-1 with $\delta P_{zu} = 0$

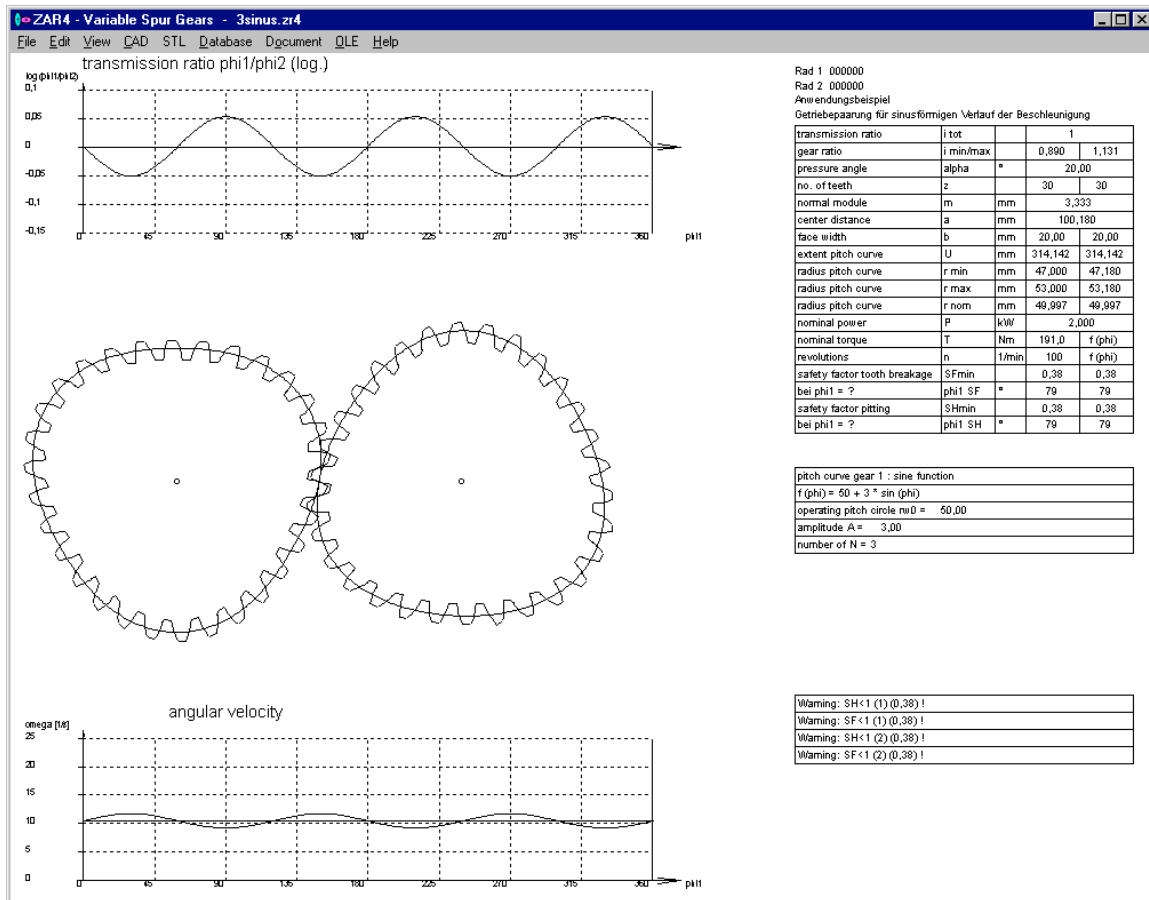
If you configure method 2 or method 3, FKR is drawn correct in the intersection point of the load-extension diagram. With method 2 („ $\delta P = \delta P + \delta P_{zu}$ “), $FKR = 10.34 \text{ kN}$ (larger than 10.3 kN of VDI). With method 3 ($\delta P_{zu} = 0$), $FKR = 9.85 \text{ kN}$ (less than 10.3 kN of VDI).

ZAR4: Quick View

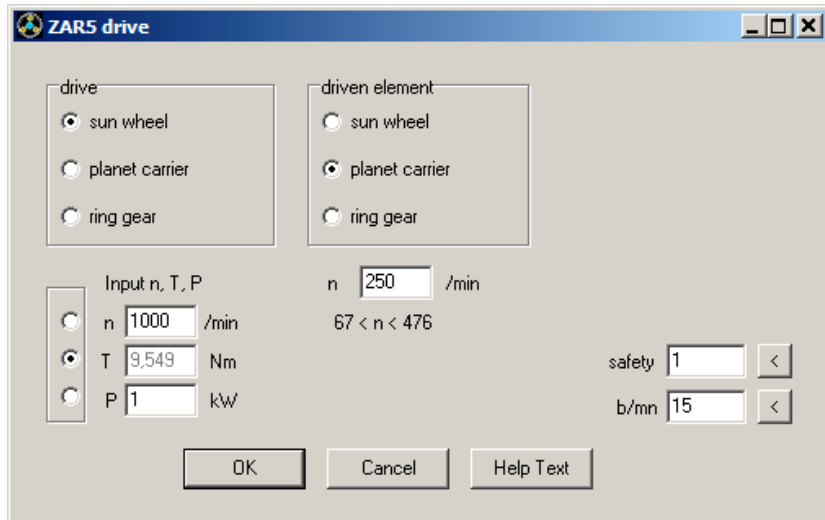
ZAR4 Software for noncircular spur gears got new Quick Views with drawing, diagrams and tables altogether on one screen.



For different screen size and resolutions different Quick View 1, 2, 3, 4 is provided. In Quick4 view, drawing, diagrams and tables are drawn together with an ISO 7200 drawing header. Quick View drawings can be loaded into CAD.



ZAR5: Pre-Dimension



In Pre-Dimension of ZAR5 you have the choice to input two of the three values speed, torque and power, and the third value is calculated.

And you can define a coefficient for safety and ratio face width / module. Safety less than 1 calculates smaller gears, and safety > 1 calculates larger planetary gears.

WN3: Shaft Stress

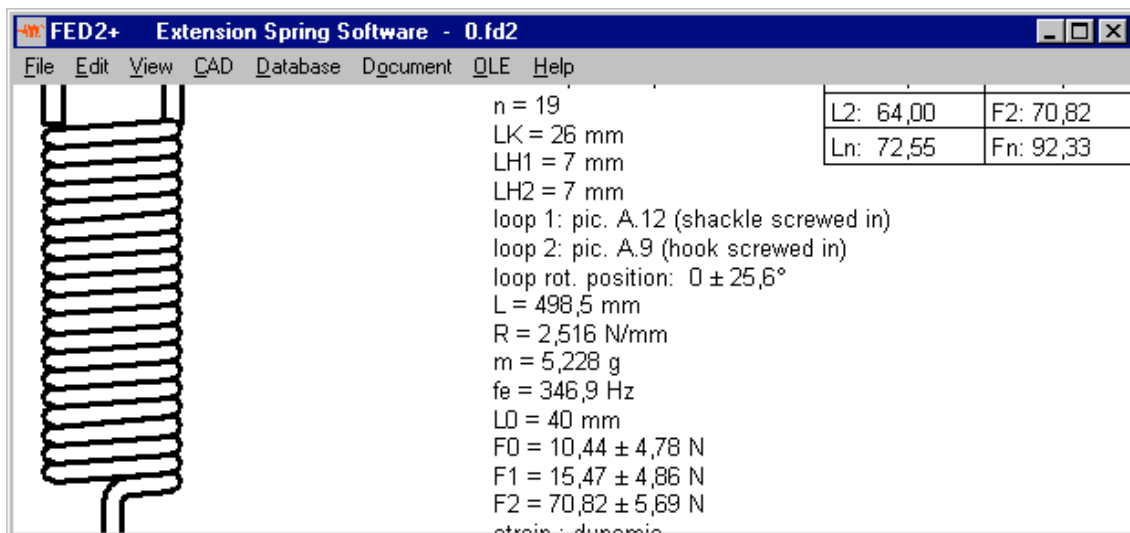
If you enter torque and additional bending moment in WN3, bending moment has no influence on pressure and safety p_{perm}/p_{max} . According to DIN 6892, WN3 calculates bending stress σ_{bmax} at the ground of the notch in the shaft from from bending moment.

WN3 now calculates reference stress of shear stress and bending stress

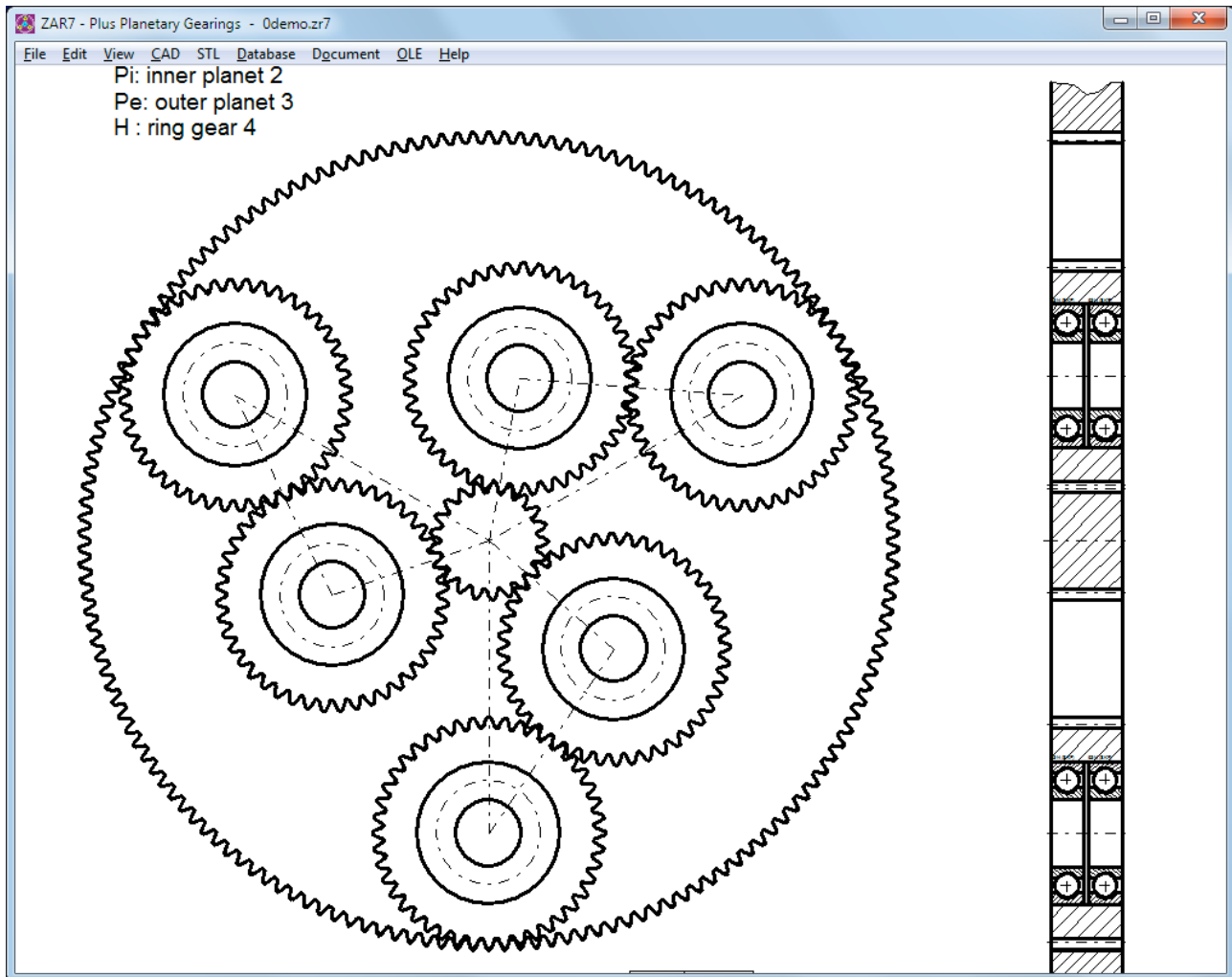
$\sigma_{mav} = \sqrt{(\sigma_{bmax}^2 + 3 * \tau_{max}^2)}$, and shows an error message if yield point of shaft material is less than reference stress.

FED2+: Quick3 with Loop position angle

Loop position rot. angle with tolerance has been added to Quick 3 View.



New Software ZAR7 for Plus Planetary Gears



A plus planetary gear set is an epicyclic gear set with planet wheel pairs instead of single planet wheels. Stationary gear ratio is positive due to reversed sense of rotation. If planet carrier is blocked, sun gear and ring gear rotate in same direction.

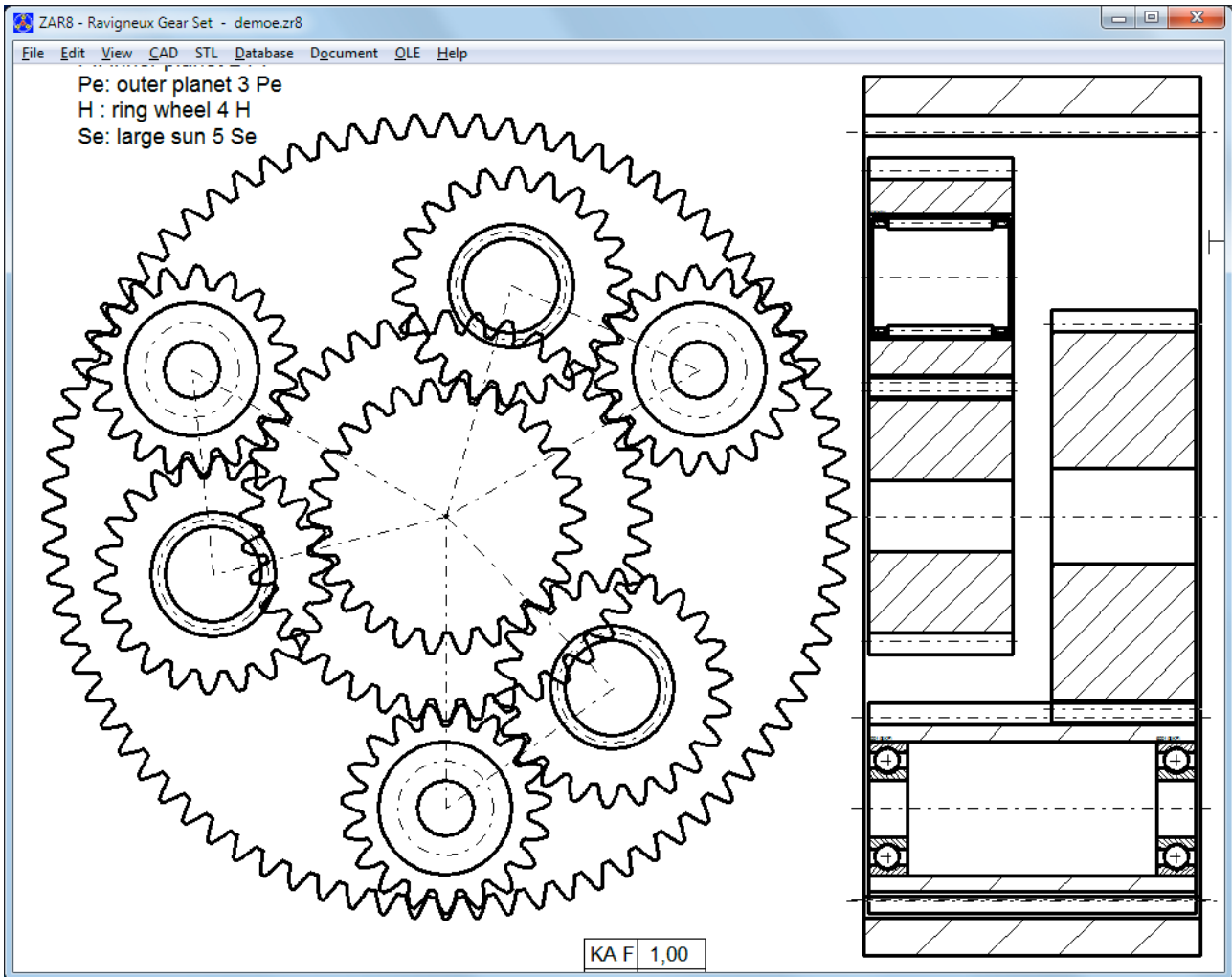
For calculation of load-bearing capacity, contact ratio, specific sliding,..., meshing gear pairs have to be calculated separately. A plus planetary gear has 3 meshes: sun wheel with inner planet wheel, inner planet wheel with outer planet wheel, outer planet wheel with ring wheel. ZAR7 calculates all gear pairs and meshes in one sequence.

Animation simulates rotating gear wheels and planet on screen.

Roller bearings for the planet wheels can be selected from included database, ZAR7 calculates bearing life expectation.

ZAR7 will be available soon.

New Software ZAR8 for Ravigneaux Planetary Gears



Ravigneaux gear sets are used in modern automatic and manual transmissions. Ravigneaux gear set is composed of two planetary gear sets: one plus planetary gear set and one simple (minus) planetary gear set. Plus and minus planetary set use a common ring gear and a common planet carrier. And the outer planet wheel of the plus planetary set is the planet wheel of the minus planetary gear set.

Ravigneaux gears have 4 ports (shafts, clutches): small sun, large sun, carrier, and ring gear. To be used as driving shaft, driven shaft, control shaft and idle shaft. If control shaft is blocked, 24 gears could be shifted in theory. Practically, Ravigneaux gears use 4 forward gears and one rear gear, and driven gear is always the ring gear.

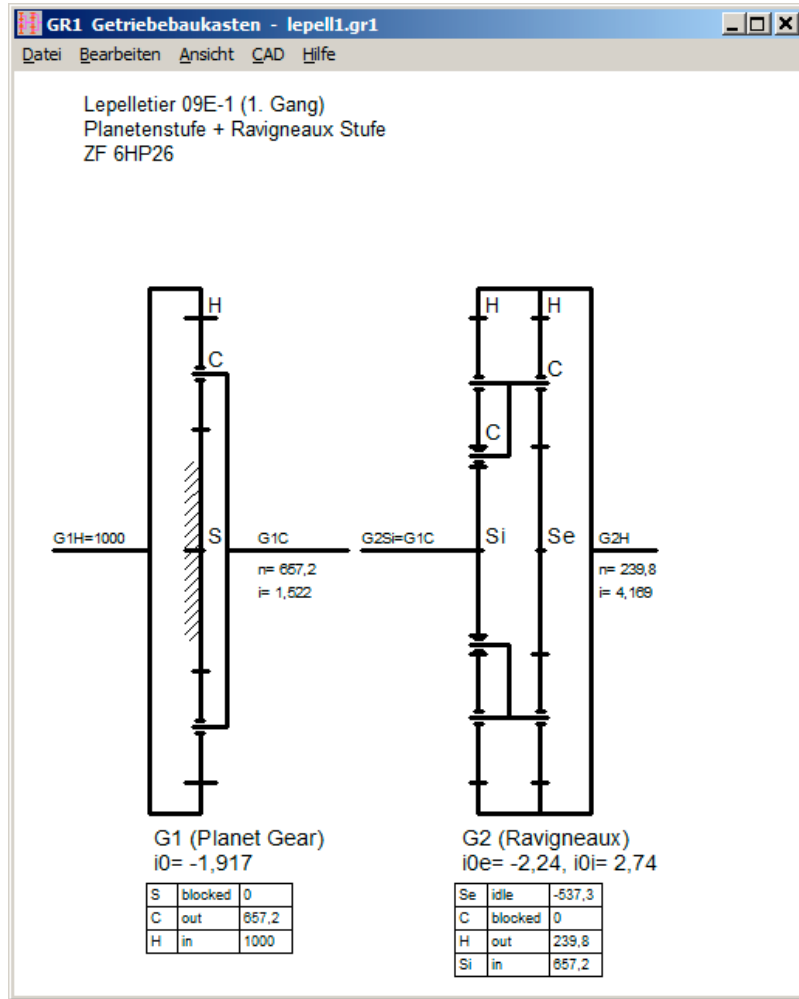
For calculation of load-bearing capacity, contact ratio, specific sliding, ..., meshing gear pairs have to be calculated separately. A Ravigneaux planetary gear has 4 meshes: small sun wheel with inner planet wheel, inner planet wheel with outer planet wheel, outer planet wheel with ring wheel, large sun wheel with outer planet.

ZAR8 calculates all gear pairs and meshes in one sequence.

Roller bearings for the planet wheels can be selected from included database, ZAR8 calculates bearing life expectation.

ZAR8 will be available soon.

New Software GR1 Gear Toolkit



GR1 calculates speed and transmission ratio of multistage gears composed of gear pairs, planetary gear sets, plus planetary gear sets, Ravigneaux planetary gear sets or Simpson planetary gear sets.

GR1 - 2

Gear Type:

- Spur/Helical Gear
- Planet Gear
- Ravigneaux
- Simpson
- Plus Planet Gear

$i_{0e} = zH/zSe (-)$

$i_{0i} = -zH/zSi (+)$

Name

n_{in}

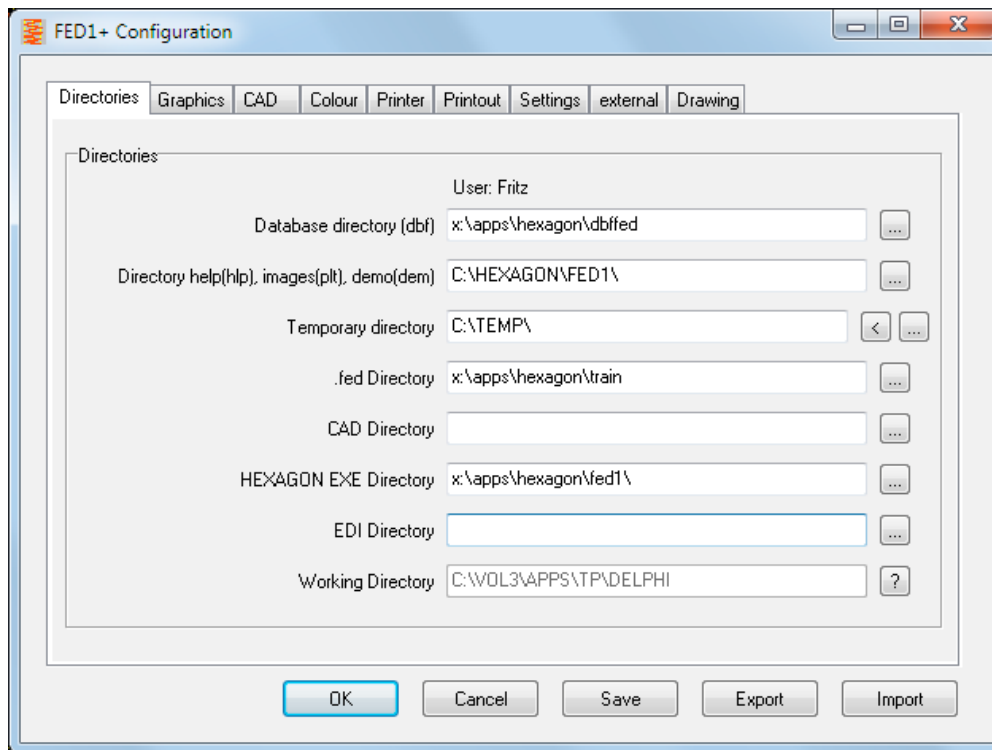
Driven by...	Gear No.	Element	n [1/min]
Sun Gear Se	<input type="text" value="idle"/>		
Planet Carrier C	<input type="text" value="blocked"/>		
Ring Gear H	<input type="text" value="out"/>		
Sun Gear Si	<input type="text" value="in"/>	<input type="text" value="1"/>	<input type="text" value="C (carrier)"/>

Buttons:

GR1 will be available soon.

Making network versions running faster

Main reason if network versions run slowly is too much network traffic: too much data sent to and requested from file server. At „File->Settings->Directories“ you can configure important settings and thus make network versions faster:



Most important setting: **Temporary directory must be a local drive!** Best choice is to configure a RAM disk.

New Option „Copy DBF -> TEMP“

Another optimization is to copy the dbf database files into a local directory and configure this local drive as database directory. But in this case an actualization problem remains: you must regularly synchronize database files, or copy from network into local drive. Therefore a new option is available now: if „copy DBF -> TEMP“ is checked, dbf files are copied at program start from R/O network directory into temporary directory, and used from temp directory during the session. Using this new option, you do not have to copy dbf files nor change configurations: database directory remains the write-protected network database directory.

If you, furthermore, copy the help files (hlp, plt, dem) into a local directory and configure this local directory (Directory help, images, demo) , you have only one network access at program start and the network version runs as fast as a locally installed individual license.

Printer Portrait-Landscape

When changing printer at “File->Printer”, sometimes the printing orientation changed into the standard setting of the new printer. This was changed now, printing orientation portrait or landscape remains unchanged when selecting another printer.

HEXAGON PRICELIST 2016-11-01

PRODUCT	EUR
DI1 Version 1.2 O-Ring Seal Software	190,-
DXF-Manager Version 9.0	383,-
DXFPLOT V 3.2	123,-
FED1+ V29.1 Helical Compression Springs incl. spring database, animation, relax., 3D,..	695,-
FED2+ V20.0 Helical Extension Springs incl. spring database, animation, relaxation, ...	675,-
FED3+ V18.7 Helical Torsion Springs incl. prod.drawing, animation, 3D, rectang.wire, ...	480,-
FED4 Version 7.2 Disk Springs	430,-
FED5 Version 15.2 Conical Compression Springs	741,-
FED6 Version 15.9 Nonlinear Cylindrical Compression Springs	634,-
FED7 Version 12.7 Nonlinear Compression Springs	660,-
FED8 Version 6.8 Torsion Bar	317,-
FED9 Version 6.0 Spiral Spring	394,-
FED10 Version 3.3 Leaf Spring (complex)	500,-
FED11 Version 3.3 Spring Lock and Bushing	210,-
FED12 Version 2.4 Elastomere Compression Spring	220,-
FED13 Version 3.9 Wave Spring Washers	185,-
FED14 Version 1.4 Helical Wave Spring	395,-
FED15 Version 1.3 Leaf Spring (simple)	180,-
FED16 Version 1.0 Constant Force Spring	225,-
GEO1+ V6.1 Cross Section Calculation incl. profile database	294,-
GEO2 V2.6 Rotation Bodies	194,-
GEO3 V3.3 Hertzian Pressure	205,-
GEO4 V4.1 Cam Software	265,-
HPGL-Manager Version 9.0	383,-
LG1 V6.4 Roll-Contact Bearings	296,-
LG2 V2.2 Hydrodynamic Plain Journal Bearings	460,-
SR1 V22.1 Bolted Joint Design	640,-
SR1+ V22.1 Bolted Joint Design incl. Flange calculation	750,-
TOL1 V11.8 Tolerance Analysis	506,-
TOL1CON V1.5 Conversion Program for TOL1	281,-
TOL2 Version 3.3 Tolerance Analysis	495,-
TOLPASS V4.1 Library for ISO tolerances	107,-
TR1 V4.0 Girder Calculation	757,-
WL1+ V19.8 Shaft Calculation incl. Roll-contact Bearings	945,-
WN1 Version 11.6 Cylindrical and Conical Press Fits	485,-
WN2 V 9.6 Involute Splines to DIN 5480	250,-
WN2+ V 9.6 Involute Splines to DIN 5480 and non-standard involute splines	380,-
WN3 V 5.4 Parallel Key Joints to DIN 6885, ANSI B17.1, DIN 6892	245,-
WN4 V 4.5 Involute Splines to ANSI B 92.1	276,-
WN5 V 4.5 Involute Splines to ISO 4156 and ANSI B 92.2 M	255,-
WN6 V 3.0 Polygon Profiles P3G to DIN 32711	180,-
WN7 V 3.0 Polygon Profiles P4C to DIN 32712	175,-
WN8 V 2.2 Serration to DIN 5481	195,-
WN9 V 2.2 Spline Shafts to DIN ISO 14	170,-
WN10 V 4.0 Involute Splines to DIN 5482	260,-
WN11 V 1.3 Woodruff Key Joints	240,-
WNXE V 2.0 Involute Splines - dimensions, graphic, measure	375,-
WNXK V 2.0 Serration Splines - dimensions, graphic, measure	230,-
WST1 V 10.0 Material Database	235,-
ZAR1+ V 25.3 Spur and Helical Gears	1115,-
ZAR2 V7.7 Spiral Bevel Gears to Klingelnberg	792,-
ZAR3 V8.9 Worm Gears	404,-
ZAR4 V5.0 Non-circular Spur Gears	1610,-
ZAR5 V11.0 Planetary Gearings	1355,-
ZAR6 V3.7 Straight/Helical/Spiral Bevel Gears	585,-
ZARXP V2.1 Involute Profiles - dimensions, graphic, measure	275,-
ZAR1W V1.7 Gear Wheel Dimensions, tolerances, measure	450,-
ZM1.V2.4 Chain Gear Design	326,-

PACKAGES	EUR
HEXAGON Mechanical Engineering Package (TOL1, ZAR1+, ZAR2, ZAR3+, ZAR5, ZAR6, WL1+, WN1, WN2+, WN3, WST1, SR1+, FED1+, FED2+, FED3+, FED4, ZARXP, TOLPASS, LG1, DXFPLOT, GEO1+, TOL2, TOL1CON, GEO2, GEO3, ZM1, WN6, WN7, LG2, FED12, FED13, WN8, WN9, WN11, D11, FED15, WNXE)	8,500.-
HEXAGON Mechanical Engineering Base Package (ZAR1+, ZAR3+, ZAR5, ZAR6, WL1+, WN1, WST1, SR1+, FED1+, FED2+, FED3+)	4.900.-
HEXAGON Spur Gear Bundle (ZAR1+ and ZAR5)	1,585.-
HEXAGON Involute Spline Package (WN2+, WN4, WN5, WN10, WNXE)	1,200.-
HEXAGON Graphic Package (DXF-Manager, HPGL-Manager, DXFPLOT)	741.-
HEXAGON Helical Spring Package (FED1+, FED2+, FED3+, FED5, FED6, FED7)	2,550.-
HEXAGON Tolerance Package (TOL1, TOL1CON, TOL2, TOLPASS)	945.-
HEXAGON Complete Package (All Programs of Engineering Package, Graphics Package, Tolerance Package, Helical Spring Package, TR1, FED8, FED9, FED10, ZAR4, GEO4, WN4, WN5, FED11, WN10, ZAR1W, FED14, WNXK, FED16)	11,500.-

Quantity Discount for Individual Licenses

Licenses	2	3	4	5	6	7	8	9	>9
Discount %	25%	27.5%	30%	32.5%	35%	37.5%	40%	42.5%	45%

Network Floating License

Licenses	1	2	3	4	5	6	7..8	9..11	>11
Discount/Add.cost	-50%	-20%	0%	10%	15%	20%	25%	30%	35%

(Negative Discount means additional cost)

Language Version:

- **German and English** : all Programs
- **French**: FED1+, FED2+, FED3+, FED4, FED5, FED6, FED7, FED9, FED10, FED14, TOL1, TOL2.
- **Italiano**: FED1+, FED2+, FED3+, FED4, FED5, FED6, FED7, FED9.
- **Swedish**: FED1+, FED2+, FED3+, FED5, FED6, FED7.
- **Portugues**: FED1+
- **Spanish**: FED1+, FED2+, FED3+

Updates:

Update prices	EUR
Software Update (software + pdf manual)	40,-
Software Update (software 64-bit Win + pdf manual)	50,-

Update Mechanical Engineering Package: 800 EUR, Update Complete Package: 1000 EUR

Maintenance contract for free updates: annual fee: 150 EUR + 40 EUR per program

Upgrades

For upgrades to network licenses or plus versions or software bundles, upgraded licenses are credited 75%.

Hexagon Software Network Licenses

Floating License in the time-sharing manner by integrated license manager

Individual licenses may not be installed in a network!

Conditions for delivery and payment

General packaging and postage costs are EUR 60, (EUR 25 inside Europe)

Delivery by Email (program packed, manual as pdf files): EUR 0.

Conditions of payment: bank transfer in advance with 2% discount, or by credit card (Master, Visa) net.

Key Code

After installation, software has to be released by key code. Key codes will be sent after receipt of payment.

HEXAGON Industriesoftware GmbH

Stiegelstrasse 8 D-73230 Kirchheim Tel.+49 702159578 Fax +49 7021 59986
 Kieler Strasse 1A D-10115 Berlin Mühlstr. 13 D-73272 Neidlingen
 Mobile: +49 163 7342509 E-Mail: info@hexagon.de Web: http://www.hexagon.de